Installing High-Torque Stepper Motors on Ball Screw Machines

High-Torque Stepper Motor Installation Instructions

In order to prevent damage during shipment, the stepper motors have not been installed. Install them using the following procedure:

1. Orient the motor so the cable is on either the left or right side of the motor to keep chips and coolant from causing a possible electrical short at the connection.

2. Note the location of the flats on the stepper motor shaft. Always assure that the coupling and handwheel set screws are tightened against the flats on the shaft. Tightening the set screw against the round part of the shaft can gall the shaft and make it impossible to remove from the coupling later.

3. Align the male coupling set screw with the access hole in the side of the stepper motor mount and assure that the set screw is sufficiently released so that the motor shaft can be inserted.

4. Insert the motor shaft into the coupling, making sure the set screw is aligned with the flat. Loosely tighten the set screw.

5. Install the four 8-32 x 3/8" socket head cap screws (SHCS) through the holes in the motor flange and into the stepper motor mount holes. Tighten all four 8-32 screws. These screws must be tightened before you tighten the set screw to the stepper motor shaft.

6. Assure that the flat on the motor shaft is still aligned with the coupling set screw (observe the position of the rear flat or handwheel set screw—the two flats are parallel) and tighten the male coupling set screw. Install and turn the handwheel and observe the movement of the leadscrew to make sure everything is turning smoothly.

Using Handwheels on the Stepper Motors

When turning an unpowered stepper motor by hand you may notice a slightly “notchy” feel because of the permanent magnets in the motor. This is normal. When the motors are powered up they lock in position, and it will be very difficult to move them with the handwheels. Therefore, if you wish to use manual mode, you should first turn off the power to the motors using the ON/OFF switch on the external driver box or on the side of the computer if the driver box is built in. Turning a DC motor by hand causes it to act as a generator, sending current backward through the circuit. However, low amounts of current will not damage the board, so avoid cranking faster than about 1 rev/second to be safe. For longer travels, use the jog mode of your CNC control software for approximate positioning, then turn off the driver box power and use the handwheel for fine tuning.

PRECAUTIONS

- Poor connections can cause arcing, which can burn out motors or control chips. Always make sure plugs and connections are fully engaged and making good contact before powering up.
- Do not pull on wires to disconnect motor. Always grasp the plastic connector or the plug itself.
- In manual mode, crank handwheel no faster than 1 rev/second to avoid back-current.

Video Instructions for Installing High-Torque Stepper Motors on Ball Screw Machines

https://youtu.be/TmfHy_Oabns

Figure 1—Components of the high-torque stepper motor and mount for ball screw machines. The motor can also be mounted with the electronic cable facing downward.
Hi-Torque Stepper Motor Mount

**Title**: Hi-Torque Stepper Motor Mount

**Sheet**: Sheerline Products, Inc.

**Dimensions**: 2.62" x 2.375" x 0.96"

**Notes**:
- Black Anodize
- Shaft: .25" Diameter
- Tapped: 8–32
- Thrust: 4 PL

**Mounting Instructions**:

To mount the motor, start by lining up the motor shaft with the coupling. Carefully insert the motor shaft into the coupling. With the flanges touching, rotate the stepper motor until the flat on the shaft is in alignment with the coupling set screw. Tighten the set screw. Rotate the motor to align with the 8–32 tapped holes. We usually attach the motor using three screws and use a zip tie in the fourth hole to secure the wire bundle.

If using a non-Sherline stepper motor, make sure to grind flats on the shaft where the coupling and handwheel set screws contact the shaft.

**Heat Treat**: None

**Angles**

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<th>Dimension</th>
<th>Tolerances</th>
<th>Notes</th>
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<tr>
<td>1.600</td>
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**Design by**: Karl Rohlin

**Check by**: Karl Rohlin

**Drawn by**: Karl Rohlin

**Rev. 2**

**Scale**: 1 = 1

**Finish**: Black Anodize

**Material**: 6061 T6

**Note**: Do Not Scale Drawing!!!

**Scale**: 1/4" = 1"
**SHERLINE HIGH-TORQUE STEPPER MOTOR SPECIFICATIONS**

- **Sherline P/N:** 67126 (w/ DIN plug and flats on shaft)
- **Frame size:** NEMA #23
- **Step angle:** 1.8°
- **Voltage:** 4.5V DC
- **Current:** 2.0 A/
- **Resistance:** 2.25 Ω/ ±10%
- **Inductance:** 3.6 mH/ ±20% mH@1kHz
- **Holding torque:** 1.35 N.m (Newton meters)
  - 13.756 kg-cm (kilogram centimeter)
  - 191.17 oz/in (ounce inch)
  - 11.948 in/lb (inch pound)
- **Axial-Force** Fa=15 N Max., or 3.37 lbf Max.
- **Radial-Force** Fr=75 N Max., or 16.86 lbf Max.
- **Rotor inertia:** 480 g-cm²
- **Number of wire leads:** 6 (See color code diagram FIG. 1)
- **Weight:** 2.2 lb (1 Kg.)
- **Length:** 4.62” (117.28 mm)
- **Shaft:** Double ended, 1/4” diameter

**Lead Wire Connection and Color Code**

![Color Code Diagram](image)

**FIGURE 1**— Color of internal wiring for high-torque motors

See figure 2 for the pin diagram and wire color layout of the stepper motor connector cables we supply with our high-torque stepper motors. Since there is no industry standard for wire colors in this field, if using a connector not supplied by Sherline each pin and color should be confirmed with a continuity tester before applying power.

**FIGURE 2:** diagram shows which pin in the DIN connector is wired to which position in the motor connector.

**NOTE:** Motors can be wired in either unipolar or bipolar configuration depending on how the leads are connected. Sherline motors with plugs are wired for unipolar operation.

**PRECAUTIONS**

- Make sure the ends of raw wires are not touching each other when turning the handwheel by hand to drive the stepper motor and leadscrew. It can cause the motor to feel rough and hard to turn.
- DC motors generate current when hand cranked that can damage the control unit. When positioning a stepper motor by hand using the handwheel, do not crank faster than about 1 rev/second. For long travels, use the jog mode of your CNC control software.
- Poor connections can cause arcing, which can burn out motors or control chips. Always make sure plugs and connections are fully engaged and making good contact.
- Always turn off driver box power before plugging in or unplugging a stepper motor.